Filing Date: January 10, 2005

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AMENDMENTS TO THE CLAIMS

This listing of claims will replace all prior versions and listings of claims in the application.

Listing of Claims:

1. (Previously presented) A thrust load enhancement device for a rotor-bearing system,

comprising:

a stator mounted on a rotation axis of the rotor-bearing system;

a rotor separated from said stator by a first air gap on the rotation axis; and

at least one permanent magnet separated from said rotor by a second air gap;

wherein said at least one permanent magnet, said stator and said rotor form a

magnetic circuit characterized by a flux path, a flux in said first and second air gaps generating a

compensation force between said rotor and said stator that opposes an external force F_{ext} .

2. (Previously presented) The thrust load enhancement device according to claim 1, wherein the

external force F_{ext} is caused by an action selected from the group consisting of pressure and

gravity in a vertical shaft configuration wherein a center of gravity is low.

3. (Original) The thrust load enhancement device according to claim 1, wherein said at least one

permanent magnet is fixed to said stator.

4. (Original) The thrust load enhancement device according to claim 1, wherein said at least one

permanent magnet is fixed to said rotor.

5. (Original) The thrust load enhancement device according to claim 1, wherein a first one of

said at least one permanent magnet is fixed to said stator and a second one of said at least one

4

permanent magnet is fixed to said rotor.

Filing Date: January 10, 2005

First Named Inventor: Lin Xiang Sun

6. (Original) The thrust load enhancement device according to claim 5, wherein said first one of

said at least one permanent magnet and said second one of said at least one permanent magnet

respectively have poles of different polarity facing each other to create an attractive

compensation force between said rotor and said stator.

7. (Original) The thrust load enhancement device according to claim 5, wherein said first one of

said at least one permanent magnet and said second one of said at least one permanent magnet

respectively have poles of a similar polarity facing each other to create an expulsion

compensation force between said rotor and said stator.

8. (Previously presented) The thrust load enhancement device according to claim 1, further

comprising a spacer to adjust said first and second air gaps.

9. (Previously presented) The thrust load enhancement device according to claim 1, further

comprising a piezoelectric actuator mounted in said stator.

10. (Previously presented) The thrust load enhancement device according to claim 1, wherein

said rotor and said stator are made in a material selected from the group consisting of a soft

magnetic material and a non-magnetic material.

11. (Previously presented) The thrust load enhancement device according to claim 1, wherein

said rotor is made of carbon steel and said stator is made of mild steel.

12. (Previously presented) The thrust load enhancement device according to claim 1, wherein the

external force is selected in the group consisting of a static force and a dynamic force.

13. (Previously presented) The thrust load enhancement device according to claim 1, further

comprising force measurement devices to measure the compensation force.

5

Filing Date: January 10, 2005

First Named Inventor: Lin Xiang Sun

14. (Currently amended) The thrust load enhancement device according to 13, wherein said force

measurement devices are selected from the group consisting of stainstrain gauges and

piezoelectric elements.

15. (Previously presented) The thrust load enhancement device according to claim 1, wherein

said load enhancement device is located at one end of a shaft of the rotor-bearing system.

16. (Previously presented) The thrust load enhancement device according to claim 1, wherein the

thrust load is unidirectional from an external working load.

17. (Previously presented) The thrust load enhancement device according to claim 1, wherein the

thrust load is unidirectional from a rotor weight in a vertical configuration.

18. (Previously presented) The thrust load enhancement device according to claim 1, wherein the

external force is an unidirectional external static load selected from the group consisting of a

working load and a shaft weight in a vertical configuration.

19. (Previously presented) The thrust load enhancement device according to claim 1, wherein the

rotor-bearing system is selected from the group consisting of a magnetic bearing system, a

hydrostatic bearing system, a hydrodynamic bearing system, and a rolling element bearing

system.

20. (Original) A method for thrust load enhancement for a rotor-bearing system comprising the

steps of:

providing a stator on a rotation axis of the rotor-bearing system;

providing a rotor separated on the rotation axis from the stator by a first air

gap; and

Filing Date: January 10, 2005

First Named Inventor: Lin Xiang Sun

providing at least one permanent magnet separated from the rotor by a

second air gap,

whereby the at least one permanent magnet, the stator and the rotor form a

magnetic circuit characterized by a flux path so that a flux in the first and second air gaps

generates a compensation force between the rotor and the stator that opposes an external force

 F_{ext}

21. (Previously presented) The method for thrust load enhancement according to claim 20,

wherein said steps of providing a stator and said step of providing a rotor comprise providing a

rotor and a stator made in a material selected from the group consisting of a soft magnetic

material and a non-magnetic material.

22. (Original) The method for thrust load enhancement according to claim 20, wherein said step

of providing a stator comprises providing a stator made of mild steel and said step of providing a

rotor comprises providing a rotor made of carbon steel.

23. (Original) The method for thrust load enhancement according to claim 20, wherein said step

of providing at least one permanent magnet comprises mounting at least one permanent magnet

on the stator.

24. (Original) The method for thrust load enhancement according to claim 20, wherein said step

of providing at least one permanent magnet comprises mounting at least one permanent magnet

on the rotor.

25. (Original) The method for thrust load enhancement according to claim 20, wherein said step

of providing at least one permanent magnet comprises fixing a first one of the at least one

permanent magnet to the stator and a second one of the at least one permanent magnet to the

rotor.

7

Filing Date: January 10, 2005

First Named Inventor: Lin Xiang Sun

26. (Original) The method for thrust load enhancement according to claim 25, wherein said steps

of fixing a first one of the at least one permanent magnet to the stator and a second one of the at

least one permanent magnet to the rotor comprise arranging respective poles of different polarity

thereof facing each other to create an attractive compensation force between the rotor and the

stator.

27. (Original) The method for thrust load enhancement according to claim 25, wherein said steps

of fixing a first one of the at least one permanent magnet to the stator and a second one of the at

least one permanent magnet to the rotor comprises arranging respective poles of similar polarity

facing each other to create an expulsion compensation force between the rotor and the stator.

28. (Previously presented) The method for thrust load enhancement according to claim 20,

further comprising a step of providing a spacer to adjust said first and said second air gaps.

29. (Previously presented) The method for thrust load enhancement according to claim 20,

further comprising the step of mounting a piezoelectric actuator in the stator.

30. (Previously presented) The method for thrust load enhancement according to claim 20,

wherein the external force is selected from the group consisting of a static force and a dynamic

force.

31. (Previously presented) The method for thrust load enhancement according to claim 20,

further comprising the step of providing force measurement devices to measure the

8

compensation force.

Filing Date: January 10, 2005

First Named Inventor: Lin Xiang Sun

32. (Currently amended) The method for thrust load enhancement according to 31, wherein said step of providing force measurement devices comprises selecting devices from the group consisting of stain-strain gauges and piezoelectric elements.

33. (Currently amended) The method for thrust load enhancement according to claim 20, wherein the rotor-bearing system is selected from the group <u>eonsisting consisting</u> of a magnetic bearing system, a hydrostatic bearing system, a hydrodynamic bearing system, and a rolling element bearing system.